

# Fast Wake Algorithm Derivation

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The fundamental linearized fluid dynamic equations are

$$\frac{\partial h(\vec{x}, t)}{\partial t} = (-\partial^2)^{1/2} \phi(\vec{x}, t) \quad (1)$$

$$\frac{\partial \phi(\vec{x}, t)}{\partial t} = -gh(\vec{x}, t) + S(\vec{x} - \vec{u}t) \quad (2)$$

with the definitions:

- $h$  is the waveheight,
- $\phi$  is the velocity potential,
- $\vec{x}$  is the position on the water surface,
- $t$  is time,
- $S$  is the shape of the wake source,
- $\vec{u}$  is the source velocity,
- $g$  is the gravitational constant

We solve this by taking the FFT in space and time, to get

$$\tilde{h}(\vec{k}, \omega) = \frac{1}{g} \frac{\tilde{S}(\vec{k})}{1 - \omega^2/gk} \delta(\omega - \vec{u} \cdot \vec{k}) \quad (3)$$

Now doing the temporal frequency integral, we have

$$\tilde{h}(\vec{k}, t) = \exp(-i\vec{k} \cdot \vec{u}t) \frac{1}{g} \frac{\tilde{S}(\vec{k})}{1 - (\vec{u} \cdot \vec{k})^2/gk} \quad (4)$$

Now all that needs to be done is build the source shape in Fourier space, and apply it here in the inverse fft. Just be carefull of the pole.