VISUALIZATION OF SIMULATED OCEAN SCENES EMPLOYING WHITECAP FRACTION PHENOMENOLOGY

Jerry Tessendorf Liang Gao Clemson University



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Colin Reinhardt Naval Information Warfare Center







Overview

- Constructing & simulating ocean surfaces
- Light Transport Rendering via Monte Carlo \bullet
- Representating whitecaps using a thresheld parameter

Threshold selection using statistical models of whitecap fraction

- Rendered ocean with whitecaps
- Conclusions



Part II





Constructing & Simulating Ocean Surfaces

Christopher J. Horvath. 2015. "Empirical Directional Wave Spectra for Computer Graphics." 2015 Symposium on Digital Production (DigiPro '15). ACM, New York, NY, USA, 29–39 J. Tessendorf, 2004, "Simulating Ocean Water", https://people.cs.clemson.edu/~jtessen/reports/papers_files/coursenotes2004.pdf

Bernoulli equation with a dispersion relationship

$$h(\mathbf{x}) = \int \frac{d^2k}{2\pi^2} \left\{ h_{\mathbf{k}} \ e^{i\omega_{\mathbf{k}}t} + h_{-\mathbf{k}}^* \ e^{-i\omega_{-\mathbf{k}}^*t} \right\}$$

Fourier transform implemented numerically using Fast Fourier transform on a patch of ocean

$$h(\mathbf{x}) = FFT\left\{h_{\mathbf{k}} \ e^{i\omega_{\mathbf{k}}t} + h_{-\mathbf{k}}^{*} \ e^{-i\omega_{-\mathbf{k}}^{*}t}\right\}$$

- Periodicity of FFT provides arbitrary tiling over vast regions, with repetitive features.
- environment.

$$h(\mathbf{x},t) = 2$$



Ocean surface height displacement is a random realization of a spectrum in Fourier space, evolving via linearized

$$e^{i\mathbf{k}\cdot\mathbf{x}} \quad \frac{\langle h_{\mathbf{k}} \rangle = 0}{\langle |h_{\mathbf{k}}|^2 \rangle \propto P(\mathbf{k})} \quad \omega_{\mathbf{k}}^2 = g|\mathbf{k}| \tanh(|\mathbf{k}|d)$$

Linearly adding multiple height fields suppresses repetition with more control over simulation of the maritime

$$h_i(\mathbf{x}, t)$$





Horizontal Displacement

J. Tessendorf, 2004, "Simulating Ocean Water", https://people.cs.clemson.edu/~jtessen/reports/papers_files/coursenotes2004.pdf

Gerstner-wave-like horizontal displacement derives from velocity potential $\,\phi({f x},t)$ $\mathbf{D}(\mathbf{x},t) = \int_{0}^{t} dt' \, \mathbf{V}(\mathbf{x},t)$

$$\mathbf{V}(\mathbf{x},t) = \nabla_{\mathbf{x}} \phi(\mathbf{x},t)$$

$$\mathbf{X}(\mathbf{x},t) = \mathbf{x} + \mathbf{D}(\mathbf{x},t) \qquad \mathbf{D}(\mathbf{x}) = f_{cusp} \operatorname{FFT} \left\{ i \frac{\mathbf{k}}{|\mathbf{k}|} \left(h_{\mathbf{k}} e^{i\omega_{\mathbf{k}}t} + h_{-\mathbf{k}}^{*} e^{-i\omega_{-\mathbf{k}}^{*}t} \right) \right\}$$

Horizontal displacement alters surface area via Jacobian with eigenvalues

$$\nabla_{\mathbf{x}} \mathbf{X}(\mathbf{x}, t) = \begin{bmatrix} 1 + \frac{\partial D_x}{\partial x} & \frac{\partial D_x}{\partial z} \\ \frac{\partial D_z}{\partial x} & 1 + \frac{\partial D_z}{\partial z} \end{bmatrix}$$

Minimum eigenvalue is a sensitive measure of steep peaks ullet

- No displacement:
- Near sharp peaks: $\lambda_{min}
 ightarrow 0$
- Broad troughs:

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 $\lambda_{min} = \lambda_{max} = 1$ $\lambda_{min} \geq 1$

 $\det\left(\nabla_{\mathbf{x}} \mathbf{X}(\mathbf{x},t)\right) = \lambda_{max} \ \lambda_{min}$







Minimum Eigenvalue and Wave Height





Light Transport Rendering via Monte Carlo

Pharr, Jacob, Humphreys, 2018, PHYSICALLY BASED RENDERING, <u>https://pbr-book.org</u> Dutre, Bekaert, Bala, 2003, ADVANCED GLOBAL ILLUMINATION, A.K. Peters Ltd.

- Well-established theory of Global Illumination, derived from radiative transfer for surfaces
- Integral equation relating incoming, emitted, and outgoing radiance at each point and direction on each surface

$$L_O(\mathbf{p}, \hat{\mathbf{n}}) = \int d\Omega' B(\mathbf{p}, \hat{\mathbf{n}}, \hat{\mathbf{n}})$$

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- Implemented using ray path tracing and Monte Carlo reflection, refraction & emission of rays to/from surfaces.
- Normal calculations at full simulation resolution ("Normal Mapping for Rendering Vast Oceans", paper in progress)
- Fresnel reflection & refraction
- Ocean surface tessellated into triangles with increasing size further from camera.
- Hyperspectral channels, polarization, and volume scatter possible



$\hat{\mathbf{n}}') |\hat{\mathbf{n}}_S \cdot \hat{\mathbf{n}}'| L_I(\mathbf{p}, \hat{\mathbf{n}}') + L_E(\mathbf{p}, \hat{\mathbf{n}})$







360 degree camera 2m above mean ocean surface Equirectangular projection 3cm triangles near-camera, 10+m triangles near-horizon Full resolution normal mapping Round earth Image-based RGB lighting

3 cm triangles



Rendered synthetic oceanscape without whitecaps

10+ m triangles









Representing Whitecaps using a Thresheld Parameter

Egbert S. Tse, John McGill, and Robert L. Kelly. 1990. Coherent whitecap and glitter simulation model. In Ocean Optics X, Richard W. Spinrad (Ed.), Vol.1302.InternationalSocietyforOpticsandPhotonics,SPIE,505–519. https://doi.org/10.1117/12.21468

- Dynamically updated map O of whitecap content with growth and decay
- Decay mechanism: exponential damping with half-life T
- \bullet
- "Dynamical Update" from time t to next:

 $O(\mathbf{x}, t + \Delta t) = \begin{cases} 1 \\ 0 \\ 0 \end{cases}$

 $O(\mathbf{x}, t + \Delta t) = O(\mathbf{x}, t) e^{-\Delta t/T} + \Theta(\lambda)$

Heaviside Step Function $\Theta(q) =$



Growth mechanism: map value boosted where & when minimum eigenvalue crosses threshold

$$\lambda_{min}(\mathbf{x}, t + \Delta t) < \lambda_T \qquad \text{(Growth)}$$

$$P(\mathbf{x}, t) \ e^{-\Delta t/T} \quad \lambda_{min}(\mathbf{x}, t + \Delta t) \ge \lambda_T \qquad \text{(Decay)}$$

$$A_T - \lambda_{min}(\mathbf{x}, t + \Delta t)) \quad \left(1 - O(\mathbf{x}, t)e^{-\Delta t/T} + \Delta t\right) \left(1 - O(\mathbf{x}, t)e^{-\Delta t/T} + \Delta t\right)$$

$$\begin{cases} 1 \quad q > 0 \\ 0 \quad q < 0 \end{cases}$$



Maps from Arbitrary Minimum Eigenvalue Thresholds Whitecap fraction W = average of map value over the domain of the map



W = 0.011 $\lambda_T = 0.71$





W = 0.15 $\lambda_T = 0.81$





Previous work

Minimum eigenvalue threshold (With time history)

Jacobian-determinant-based shader (2012) (Does not include grow+decay)





RenderWorld Scene Simulator (1996)

(same surface)

Real-time Animation and Rendering of Ocean Whitecaps

Jonathan Dupuy, Eric Bruneton

https://hal.inria.fr/hal-00967078/file/Whitecaps-presentation.pdf

#421399 : rd.rico:OceanPreCmp-0010 - 12:42 Jul 27 SUPERMAN RETURNS R&D clip (2005)



 $\alpha = +0.3$

 $\alpha = +0.7$





Jacobian-determinant-based game tools (2017) (Includes grow+decayy)



Crest: Novel ocean rendering techniques in an open source framework

> Huw Bowles, Daniel Zimmermann, Chino Noris, Beibei Wang

https://advances.realtimerendering.com/s2017/index.html



Threshold Selection via Statistical Models of Whitecap Fraction

observations. Atmospheric Chemistry and Physics 16, 21 (2016), 13725–13751. https://doi.org/10.5194/acp-16-13725-2016

- Assuming statistical stationarity and homogeneity,
- statistical de-correlation of minimum eigenvalue fluctuations from whitecap map fluctuations

$$W = W\alpha + \text{CDF}(\lambda_T) (1 - W\alpha)$$

- Model allows solving for threshold value to achieve selected W on average.
- Strategy:

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- 1. From simulated frame(s), extract minimum eigenvalue probability density function (PDF) via histogram of values.
- 2. Integrate PDF it into the CDF
- 3. For desired W, 🖈 determine needed CDF value.
- 4. For derived CDF value, extract threshold of minimum eigenvalue. This determines a value for λ_T $\,$ $\,$ $\,$

Oceanographic studies and models relate average whitecap fraction W to spectral parameters like wind speed U. M. F. M. A. Albert, M. D. Anguelova, A. M. M. Manders, M. Schaap, and G. de Leeuw. 2016. Parameterization of oceanic whitecap fraction based on satellite

> $\therefore W = 3.84 \times 10^{-6} U^{3.41}$ (MOM 83)

$$W = \langle O(\mathbf{x}, t) \rangle$$

Averaging dynamical update model relates W to the threshold cumulative distribution function (CDF), assuming

$$\square \operatorname{CDF}(\lambda_T) = \langle \Theta \left(\lambda_T - \lambda_{min} \right) \rangle = \int_0^{\lambda_T} d\lambda \ P$$

$$\frac{W(1-\alpha)}{1-W\alpha} = \operatorname{CDF}(\lambda_T)$$

$$\alpha = \exp(-\Delta t/T)$$

PDF and CDF of Simulated Ocean Surfaces Minimum Eigenvalue statistics

Simulated Whitecap Fraction vs Model

- MOM 83 whitecap fraction model 0
- 105 simulation runs using TMA spectrum
- 10 second run-up. W averaged over last 3.3 seconds

Parameter	Range
Half life T (sec)	{ 1, 8 }
Cusp scale f_{cusp}	{ 0.01, 0.95 }
Wind speed U (m/s)	{ 4, 25 }
Wind direction (deg)	{ 0, 359 }
Fetch (km)	{ 25, 200 }
Patch size (m)	{400,4000}
Patch dimensions (pixels)	2048 X 2048
Bottom depth (m)	{100,1000000}

Whitecap Fraction W

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Parameter	Val
Half life T (sec)	1.
Cusp scale f _{cusp}	2.
Wind speed U (m/s)	4.5
Wind direction (deg)	16
Fetch (km)	26
Depth (m)	10
MOM 83 W	0.00
Actual W	0.00
Threshold	0.0

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Grazing camera FOV (90 deg)

Grazing look Camera altitude: 5m FOV: 90 deg

Nadir look Camera altitude: 600m FOV: 90 deg

Grazing camera position X

Parameter	Va
Half life T (sec)	
Cusp scale <i>f</i> _{cusp}	2
Wind speed U (m/s)	4.
Wind direction (deg)	KOT PI
Fetch (km)	26
Depth (m)	1
MOM 83 W	0.0
Actual W	0.0
Threshold	0.0

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Grazing look Camera altitude: 5m FOV: 90 deg

Grazing camera FOV (90 deg)

Grazing camera position

Va Va
All and
0.5
24
18
3-
100
0
0.0
0.5

tecaps_r1000_overhead.0300.exr 0001

Conclusions

- This approach to threshold parameter selection tracks with assumed whitecap fraction model
- Statistical de-correlation assumption should be evaluated in more detail
- PDF-to-CDF-to-Threshold process is applicable to other choices of physical parameter (e.g. surface acceleration, curvature, jacobian)
- Could be extended to use whitecap fraction models with more dependence one spectral properties.
- Work underway to validate and extend using whitecap measurement sets

